



the product structures (e.g., single level system, serial, assembly, and general systems) and the capacity structures (e.g., uncapacitated, capacitated single resource, and capacitated multiple resources). Many researchers have studied the lot-sizing problems and designed a lot of optimal or heuristic lot-sizing procedures (e.g., references [1–9] are some excellent reviewing papers on lot-sizing problems).

Table 1 gives a brief review of some important or reviewing literatures for the different categories of the capacitated lot-sizing problems. Because the problems are NP-hard and even the feasibility problems with setup times are also NP-hard [3], most of the lot-sizing procedures and algorithms use heuristic techniques to solve the problems. However, the heuristic lot-sizing techniques for capacitated production systems usually concentrate on optimizing the production operations stage by stage, and/or only consider some simple product structures and/or simple capacity constraints. For example, the capacitated lot-sizing problems for general product structures and multiple resources are seldom considered. This is obviously an obstacle to the application of these lot-sizing techniques in real production planning and scheduling environments.

Table 1. Different capacitated lot-sizing problems and some important/reviewing literature.

Product Structure	Uncapacitated	Single Resource	Multiple Resources
Single Level	[2,10,11]	[12–16]	
Serial	[2,17]	[17]	
Assembly	[2,18–20]	[3,21–23]	
General	[2,24,25]	[6,26]	[27,28]

In the last decade, the genetic algorithm (GA), which is a search technique based on the mechanics of natural selection and natural genetics, is recognized as a powerful and widely applicable optimization method, especially for global optimization problems and NP-hard problems [29–31]. Recently, a lot of researchers studied the applications of GA for solving the lot-sizing problems with unlimited capacity [32–34] and with capacity constraints [35–42]. Numerical results obtained using these methods show that GA (probably combined with other meta-heuristics) is an effective approach to deal with the lot-sizing problems.

Before using GA to solve an optimization problem, there are two important points which must be addressed clearly: the first is the encoding (representation) scheme for the decision variables of the optimization problem, and the second is the evaluation scheme for the specific individual (chromosome) of the problem. These two schemes are interrelated and their improper combination can make GA unable to deal with the optimization problems efficiently, especially for the optimization problems with nontrivial constraints as in the general capacitated lot-sizing problems. For the capacitated lot-sizing problems, constraints that cannot be violated can be implemented by the penalty method and the decoder method. The penalty method imposes penalties on individuals that violate the constraints, while the decoder method creates decoders of the representation that avoid creating individuals violating the constraints [31]. Since each optimization problem has its own features, it is also recognized that better performance can be obtained when the problem-specific knowledge is incorporated into the simple GA [31]. In fact, there are some fundamental limitations to genetic algorithms according to the so-called No-Free-Lunch theorem [43–45]. One of the most significant implications of the No-Free-Lunch theorem is that algorithms should be matched to the search problem at hand. “If no domain-specific knowledge is used in selecting an appropriate representation, the algorithm will have no opportunity to exceed the performance of an enumerative search” [43]. Generally speaking, a better solution can be gained with deeper domain-knowledge being incorporated. However, the domain-knowledge of a specific optimization problem is usually too vast to be considered

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