

Contents lists available at SciVerse ScienceDirect

Expert Systems with Applications

journal homepage: www.elsevier.com/locate/eswa



Integrated and interactive method for solving layout optimization problems

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ARTICLE INFO

Keywords:
Integrated design method
Layout optimization
Interactive design

ABSTRACT

Having a significant impact on the design of many products and industrial systems, such as the subdivision of a ship, the layout of facilities in a plant or further still the assembly of parts of a mechanism, layout design optimization is at the heart of scientific issues. The design of an optimal layout solution is a critical and complex task due to the increasing demands of designers working on varied projects. This paper proposes an integrated approach to solve layout optimization problems, from the needs expressed by the designer to the creation of an ideal solution. This generic and interactive method is based on a design process divided into four steps: the description, the formulation, the solving of the problem, and the final decision. This process is based on a multiobjective modular optimization strategy that combines a genetic algorithm with local optimization modules. The method described in this paper is interactive because the designer participates in all process's steps. For example, in the final decision step, the approach includes an interactive environment in order to let the designer choose and improve an optimal solution according to his personal judgment and expertise. The global method is applied to an industrial problem which deals with the search for an optimal layout of facilities in a shelter.

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1. Introduction

Layout problem is inherently a multidisciplinary task. It covers all the aspects of the product design life cycle from the conceptual to the detailed stage and makes necessary the collaboration between experts of technical and economical disciplines. Layout problems are usually considered as optimization problems. Although there are, in layout design literature, different definitions of layout optimization problems (Cagan, Shimada, & Yin, 2002; Yi, Fadel, & Gantovnik, 2008), the key idea is always the same: given a set of free form components and an available space, a layout problem consists of finding the best arrangement (location and orientation) of components satisfying geometrical and functional constraints and achieving design objectives. This generic definition can be adapted to all real-world applications. For example, Drira, Pierreval, and Hajri-Gabouj (2007) and Wäscher, Haubner, and Schumann (2007) have adapted the definition of a layout problem to their respective research domain, meaning the facility layout design and the cutting and packing problems. Solving layout optimization problems is critical hard because layout problems are generally considered as non-linear and NP-hard optimization problems. Problems are intrinsically harder than those which can be solved by a non-deterministic turing machine in polynomial

time. Consequently, designers need efficient tools in order to formulate and solve these optimization problems and make a final decision. As far as we know, there is no existing paper in literature which proposes a generic integrated method for solving layout problems.

Regarding the optimization algorithms used to solve layout problems, one finds multiple single or multi-objective approaches in two or three dimensions Cagan et al. (2002). Traditional gradient-based approaches can be used for simple layout problems. For more complex real-world applications, some stochastic algorithms are required to avoid local optima. For example, some optimization strategies use genetic algorithms (Aiello, La Scalia, & Enea, 2012; Al Hakim, 2000; Grignon & Fadel, 2004; Islier, 1998; Yi et al., 2008), simulated-annealing algorithms (Sahin, 2011; Szykman & Cagan, 1997) or extended pattern search algorithms (Su & Cagan, 2000). Most search algorithms are developed for a specific problem and they provide an effective optimization strategy for it. However, they are not generic and cannot be adapted to a lot of layout problems. Some of recent studies deal with the search of efficient generic algorithms for solving layout problems. Jacquenot et al. propose in Jacquenot, Bennis, Maisonneuve, and Wenger (2009) an hybrid algorithm based on a genetic algorithm coupled with a separation algorithm. A variant of this approach is also presented in Benabes, Bennis, Poirson, and Ravaut (2010).

In the solving process of layout problems, the direct participation of the designer in the construction of an ideal solution is an essential stage. Non-formal analysis has to be integrated in the

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85 search for an optimal design. In general, the designer almost al-
 86 ways has to correct either the design variables, the optimization
 87 criteria, and so on. We can find in Michalek and Papalambros
 88 (2002) a significant contribution to the integration of the designer
 89 in the layout optimization process. The method is applied to archi-
 90 tectural layouts, and designer suggests to the optimization algo-
 91 rithm initial solutions which take into account his own expertise.
 92 Moreover, interactivity with designer can be used to insert qualita-
 93 tive fitness or user perceptions in the design process (Poirson et
 94 al.). In layout design, Brintrup et al. have already developed an
 95 interactive genetic algorithm based framework for handling qualita-
 96 tive criteria in design optimization (Brintrup, Ramsden, & Tiwari,
 97 2007). Also, the designer can interact with the optimization pro-
 98 cess in order to make a final choice on the alternatives proposed
 99 by the optimization algorithm. Interactive decision making envi-
 100 ronments are necessary to make this final choice (Balling, Buffalo,
 101 & NY.; Stump, Yukish, Simpson, & Harris, 2003). According to
 102 the analysis of existing work on layout optimization, this paper pro-
 103 poses an innovative integrated and interactive optimization meth-
 104 od for solving layout problems, from the description of the layout
 105 problem to the final decision. The paper is organized as follows.
 106 Section 2 is dedicated to the description of the different steps of
 107 the method. In Section 3, the method is applied to an industrial lay-
 108 Q6 out application. Section 5 concludes this paper.

109 **2. Presentation of the method**

110 **2.1. General view of the methodology**

111 Cagan et al. already proposed in Cagan et al. (2002) a schematic
 112 representation of the major constituent parts for solving a generic
 113 layout optimization problem but not focus on the solving process.
 114 Fig. 1, using the structured analysis and design technique (SADT),
 115 illustrates another representation of layout optimization by includ-
 116 ing the different steps of the solving process. The integrated meth-
 117 od, proposed in this paper, is based on this representation. The
 118 method is divided in four steps: the description, the formulation,
 119 the solving of the problem and the decision making. The first two
 120 steps consist in writing the optimization problem, meaning the
 121 optimization variables, the constraints and the objectives, taking

122 into account the different requirements of the designer. A geomet-
 123 ric model of the layout is created, based on an innovative division
 124 of layout components in material and virtual items. Then, an opti-
 125 mization algorithm is used in order to solve the optimization prob-
 126 lem. A set of Pareto-optimal solutions is generated if a multi-
 127 objective formulation of the problem is adopted by the designer.
 128 The final step allows the designer to make a final decision on the
 129 optimal solutions proposed by the algorithm. This decision is made
 130 according to the quantitative performances of the Pareto-optimal
 131 solutions and the personal judgment of the designer. Next sections
 132 will detailed the different steps.

133 **2.2. Description and formulation of layout problems**

134 Describing the problem is an essential step in the process of
 135 optimization. However, this is much more difficult than it seems,
 136 to equate the different components between them.

137 **2.2.1. Description of layout problem**

138 The layout problem description is the first step of the global lay-
 139 out solving process. This step is usually defined by the engineering
 140 experts who well know the global performances of the product or
 141 the system. The layout problem description includes the descrip-
 142 tion of the container, the components and the expert's require-
 143 ments. In layout problems, one finds at least one container and
 144 multiple components which have to be placed into the container.
 145 Generally, layout components are very different according to their
 146 shape, their size and their functional properties. In order to take
 147 into account these differences, we propose to divide layout compo-
 148 nents into two categories: the "material" and "virtual" compo-
 149 nents, defined as:

- 150 - **material component:** with a mass, it cannot overlap with
 151 another material component (in 2D). Layout components are
 152 generally considered as material components in layout litera-
 153 ture (Dira et al., 2007; Yi et al., 2008);
- 154 - **virtual component:** without mass, it can overlap with some
 155 material or virtual components, according to the designer's
 156 requirements. The passages, described in the layout problem
 157 presented in Lee, Han, and Roh (2003) can be considered as vir-
 158 tual components.

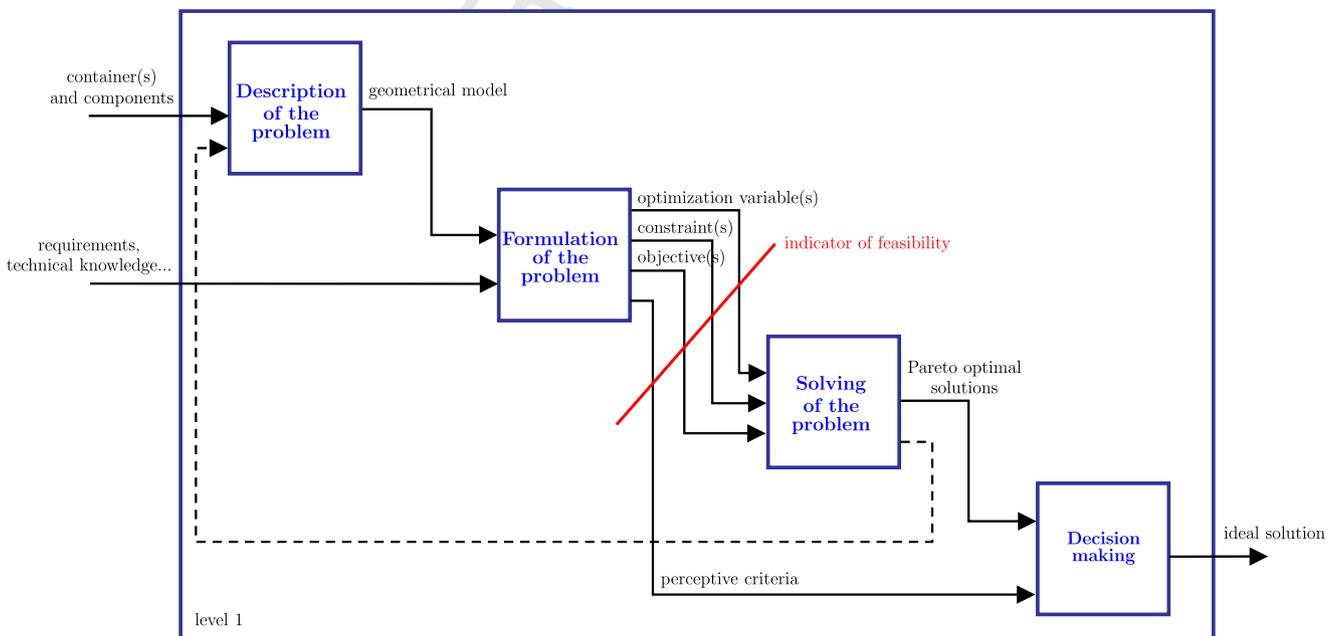


Fig. 1. SADT of the integrated layout optimization method.

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