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Integrated and interactive method for solving layout optimization problems

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ABSTRACT

Having a significant impact on the design of many products and industrial systems, such as the subdivision of a ship, the layout of facilities in a plant or further still the assembly of parts of a mechanism, layout design optimization is at the heart of scientific issues. The design of an optimal layout solution is a critical and complex task due to the increasing demands of designers working on varied projects. This paper proposes an integrated approach to solve layout optimization problems, from the needs expressed by the designer to the creation of an ideal solution. This generic and interactive method is based on a design process divided into four steps: the description, the formulation, the solving of the problem, and the final decision. This process is based on a multiobjective modular optimization strategy that combines a genetic algorithm with local optimization modules. The method described in this paper is interactive because the designer participates in all process's steps. For example, in the final decision step, the approach includes an interactive environment in order to let the designer choose and improve an optimal solution according to his personal judgment and expertise. The global method is applied to an industrial problem which deals with the search for an optimal layout of facilities in a shelter.

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1. Introduction

Layout problem is inherently a multidisciplinary task. It covers all the aspects of the product design life cycle from the conceptual to the detailed stage and makes necessary the collaboration between experts of technical and economical disciplines. Layout problems are usually considered as optimization problems. Although there are, in layout design literature, different definitions of layout optimization problems (Cagan, Shimada, & Yin, 2002; Yi, Fadel, & Gantovnik, 2008), the key idea is always the same: given a set of free form components and an available space, a layout problem consists of finding the best arrangement (location and orientation) of components satisfying geometrical and functional constraints and achieving design objectives. This generic definition can be adapted to all real-world applications. For example, Drira, Pierreval, and Hajri-Gabouj (2007) and Wäscher, Haubner, and Schumann (2007) have adapted the definition of a layout problem to their respective research domain, meaning the facility layout design and the cutting and packing problems. Solving layout optimization problems is critical hard because layout problems are generally considered as non-linear and NP-hard optimization problems. Problems are intrinsically harder than those which can be solved by a non-deterministic turing machine in polynomial

time. Consequently, designers need efficient tools in order to formulate and solve these optimization problems and make a final decision. As far as we know, there is no existing paper in literature which proposes a generic integrated method for solving layout problems.

Regarding the optimization algorithms used to solve layout problems, one finds multiple single or multi-objective approaches in two or three dimensions Cagan et al. (2002). Traditional gradient-based approaches can be used for simple layout problems. For more complex real-world applications, some stochastic algorithms are required to avoid local optima. For example, some optimization strategies use genetic algorithms (Aiello, La Scalia, & Enea, 2012; Al Hakim, 2000; Grignon & Fadel, 2004; Islier, 1998; Yi et al., 2008), simulated-annealing algorithms (Sahin, 2011; Szykman & Cagan, 1997) or extended pattern search algorithms (Su & Cagan, 2000). Most search algorithms are developed for a specific problem and they provide an effective optimization strategy for it. However, they are not generic and cannot be adapted to a lot of layout problems. Some of recent studies deal with the search of efficient generic algorithms for solving layout problems. Jacquenot et al. propose in Jacquenot, Bennis, Maisonneuve, and Wenger (2009) an hybrid algorithm based on a genetic algorithm coupled with a separation algorithm. A variant of this approach is also presented in Benabes, Bennis, Poirson, and Ravaut (2010).

In the solving process of layout problems, the direct participation of the designer in the construction of an ideal solution is an essential stage. Non-formal analysis has to be integrated in the

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85 search for an optimal design. In general, the designer almost al- 122
 86 ways has to correct either the design variables, the optimization 123
 87 criteria, and so on. We can find in Michalek and Papalambros 124
 88 (2002) a significant contribution to the integration of the designer 125
 89 in the layout optimization process. The method is applied to archi- 126
 90 tectural layouts, and designer suggests to the optimization algo- 127
 91 rithm initial solutions which take into account his own expertise. 128
 92 Moreover, interactivity with designer can be used to insert qualita- 129
 93 tive fitness or user perceptions in the design process (Poirson et 130
 94 al.). In layout design, Brintrup et al. have already developed an 131
 95 interactive genetic algorithm based framework for handling qualita- 132
 96 tive criteria in design optimization (Brintrup, Ramsden, & Tiwari, 133
 97 2007). Also, the designer can interact with the optimization pro- 134
 98 cess in order to make a final choice on the alternatives proposed 135
 99 by the optimization algorithm. Interactive decision making envi- 136
 100 ronments are necessary to make this final choice (Balling, Buffalo, 137
 101 & NY.; Stump, Yukish, Simpson, & Harris, 2003). According to 138
 102 the analysis of existing work on layout optimization, this paper pro- 139
 103 poses an innovative integrated and interactive optimization meth- 140
 104 od for solving layout problems, from the description of the layout 141
 105 problem to the final decision. The paper is organized as follows. 142
 106 Section 2 is dedicated to the description of the different steps of 143
 107 the method. In Section 3, the method is applied to an industrial lay- 144
 108 out application. Section 5 concludes this paper. 145

109 **2. Presentation of the method**

110 **2.1. General view of the methodology**

111 Cagan et al. already proposed in Cagan et al. (2002) a schematic 146
 112 representation of the major constituent parts for solving a generic 147
 113 layout optimization problem but not focus on the solving process. 148
 114 Fig. 1, using the structured analysis and design technique (SADT), 149
 115 illustrates another representation of layout optimization by includ- 150
 116 ing the different steps of the solving process. The integrated meth- 151
 117 od, proposed in this paper, is based on this representation. The 152
 118 method is divided in four steps: the description, the formulation, 153
 119 the solving of the problem and the decision making. The first two 154
 120 steps consist in writing the optimization problem, meaning the 155
 121 optimization variables, the constraints and the objectives, taking 156

122 into account the different requirements of the designer. A geomet- 123
 124 ric model of the layout is created, based on an innovative division 125
 126 of layout components in material and virtual items. Then, an opti- 127
 128 mization algorithm is used in order to solve the optimization prob- 129
 130 lem. A set of Pareto-optimal solutions is generated if a multi- 131
 132 objective formulation of the problem is adopted by the designer. 133
 134 The final step allows the designer to make a final decision on the 135
 136 optimal solutions proposed by the algorithm. This decision is made 137
 138 according to the quantitative performances of the Pareto-optimal 139
 140 solutions and the personal judgment of the designer. Next sections 141
 142 will detailed the different steps. 143

144 **2.2. Description and formulation of layout problems**

145 Describing the problem is an essential step in the process of 146
 147 optimization. However, this is much more difficult than it seems, 148
 149 to equate the different components between them. 150

151 **2.2.1. Description of layout problem**

152 The layout problem description is the first step of the global lay- 153
 154 out solving process. This step is usually defined by the engineering 154
 155 experts who well know the global performances of the product or 156
 157 the system. The layout problem description includes the descrip- 158
 159 tion of the container, the components and the expert's require- 159
 160 ments. In layout problems, one finds at least one container and 160
 161 multiple components which have to be placed into the container. 161
 162 Generally, layout components are very different according to their 162
 163 shape, their size and their functional properties. In order to take 163
 164 into account these differences, we propose to divide layout compo- 164
 165 nents into two categories: the "material" and "virtual" compo- 165
 166 nents, defined as: 166

- 167 - **material component:** with a mass, it cannot overlap with 167
 168 another material component (in 2D). Layout components are 168
 169 generally considered as material components in layout litera- 169
 170 ture (Dira et al., 2007; Yi et al., 2008); 170
- 171 - **virtual component:** without mass, it can overlap with some 171
 172 material or virtual components, according to the designer's 172
 173 requirements. The passages, described in the layout problem 173
 174 presented in Lee, Han, and Roh (2003) can be considered as vir- 174
 175 tual components. 175

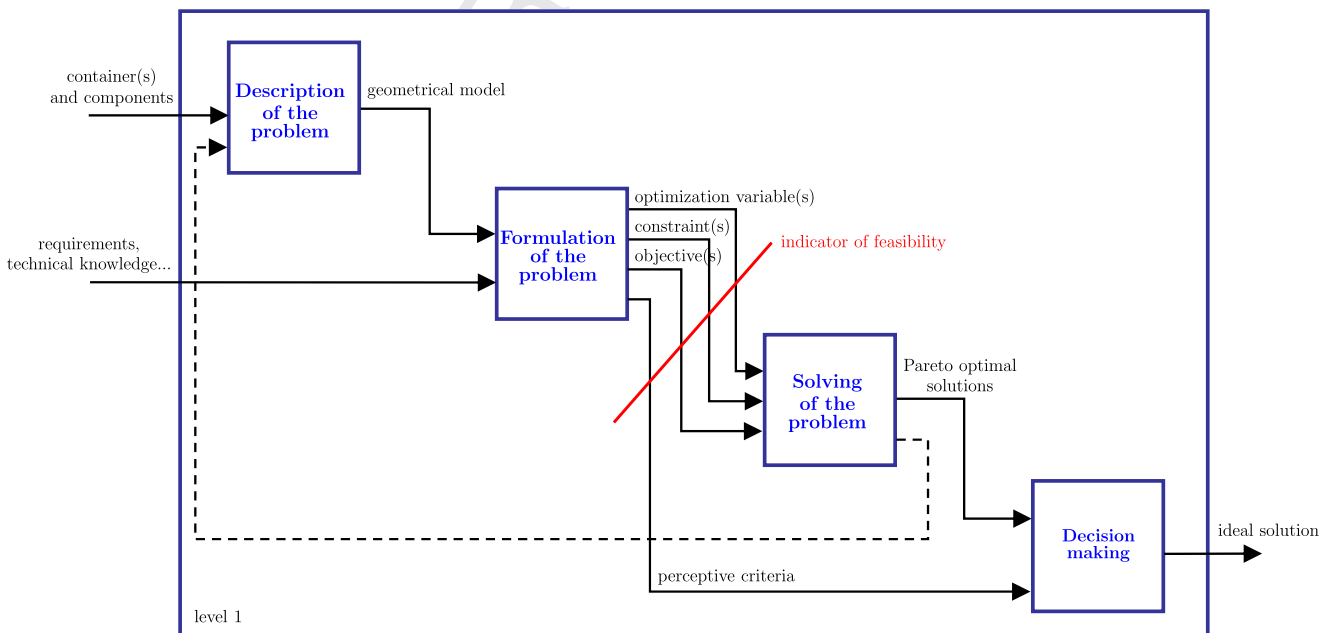


Fig. 1. SADT of the integrated layout optimization method.

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