

Accepted Manuscript

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PII: S0090-4295(17)31056-7
DOI: <https://doi.org/doi:10.1016/j.urology.2017.09.023>
Reference: URL 20684

To appear in: *Urology*

Received date: 9-6-2017
Accepted date: 8-9-2017

Please cite this article as: Jen Hoogenes, Nathan Wong, Badr Al-Harbi, Kevin S. Kim, Saahil Vij, Elisa Bolognone, Mackenzie Quantz, Yanbo Guo, Bobby Shayegan, Edward D. Matsumoto, A Randomized Comparison of Two Robotic Virtual Reality Simulators and Evaluation of Trainees' Skills Transfer to a Simulated Robotic Urethrovesical Anastomosis Task, *Urology* (2017), <https://doi.org/doi:10.1016/j.urology.2017.09.023>.

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A randomized comparison of two robotic virtual reality simulators and evaluation of trainees' skills transfer to a simulated robotic urethrovesical anastomosis task

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Keywords:

Urology; Simulation training; Robotic surgical procedures; Medical education; Urologic surgical procedures

Word count:

Abstract: 225/250

Manuscript: 2999/3000

Funding source:

McMaster Surgical Associates

ABSTRACT

Objective: To determine, via a randomized comparison study, whether robotic simulator-acquired skills transfer to performance of a urethrovesical anastomosis (UVA) on a 3D-printed bladder model using the da Vinci Robot.

Materials and methods: Medical students, surgical residents, and fellows were recruited and divided into two groups: G1 (junior trainees) and G2 (senior trainees).

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