

Accepted Manuscript

Attention Allocation for Human Multi-Robot Control: Cognitive Analysis based on Behavior Data and Hidden States

Shih-Yi Chien , Yi-Ling Lin , Pei-Ju Lee , Shuguang Han , Michael Lewis , Katia Sycara

PII: S1071-5819(18)30096-X
DOI: [10.1016/j.ijhcs.2018.03.005](https://doi.org/10.1016/j.ijhcs.2018.03.005)
Reference: YIJHC 2195



To appear in: *International Journal of Human-Computer Studies*

Received date: 1 June 2017
Revised date: 3 March 2018
Accepted date: 18 March 2018

Please cite this article as: Shih-Yi Chien , Yi-Ling Lin , Pei-Ju Lee , Shuguang Han , Michael Lewis , Katia Sycara , Attention Allocation for Human Multi-Robot Control: Cognitive Analysis based on Behavior Data and Hidden States, *International Journal of Human-Computer Studies* (2018), doi: [10.1016/j.ijhcs.2018.03.005](https://doi.org/10.1016/j.ijhcs.2018.03.005)

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Highlights

- Hidden Markov Model can effectively identify users' cognitive states and intentions
- System reliability is not the major factor to find more victims
- Attention can be efficiently directed for failures resolved but victim detection
- Users have different strategies to allocate attention in two scheduling schemes

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