

Accepted Manuscript

An efficient bicriteria algorithm for stable robotic flow shop scheduling

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PII: S0377-2217(17)30068-1
DOI: [10.1016/j.ejor.2017.01.033](https://doi.org/10.1016/j.ejor.2017.01.033)
Reference: EOR 14214



To appear in: *European Journal of Operational Research*

Received date: 18 June 2016
Revised date: 18 January 2017
Accepted date: 19 January 2017

Please cite this article as: Ada Che , Vladimir Kats , Eugene Levner , An efficient bicriteria algorithm for stable robotic flow shop scheduling, *European Journal of Operational Research* (2017), doi: [10.1016/j.ejor.2017.01.033](https://doi.org/10.1016/j.ejor.2017.01.033)

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Highlights

- We consider stable robotic scheduling with interval times and a fixed robot route.
- We minimize the cycle time and maximize the stability radius simultaneously.
- We propose a strongly polynomial algorithm to find the Pareto front.

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